



SRS50-HEA0-K22

SRS/SRM50

MOTOR FEEDBACK SYSTEMS





Ordering information

| Туре | Part no. |
|----------------|----------|
| SRS50-HEA0-K22 | 1037084 |

Other models and accessories → www.sick.com/SRS_SRM50

Illustration may differ



Detailed technical data

Safety-related parameters

| MTTF _D (mean time to dangerous failure) | 235 years (EN ISO 13849) ¹⁾ |
|--|--|

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

| Sine/cosine periods per revolution | 1,024 |
|--|---|
| Number of the absolute ascertainable revolutions | 1 |
| Total number of steps | 32,768 |
| Measuring step | $0.3{\rm ''}$ For interpolation of the sine/cosine signals with, e. g., 12 bits |
| Integral non-linearity | Typ. \pm 45 $^{\prime\prime}$, Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling |
| Differential non-linearity | ± 7 " |
| Operating speed | \leq 6,000 min ⁻¹ , up to which the absolute position can be reliably produced |
| Available memory area | 1,792 Byte |
| System accuracy | ± 52 " |

Interfaces

| Type of code for the absolute value | Binary |
|-------------------------------------|---|
| Code sequence | Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing), For clockwise shaft rotation, looking in direction "A" (see dimensional drawing) |
| Communication interface | HIPERFACE [®] |

Electrical data

| Connection type | Male connector, 8-pin, radial |
|----------------------------|-------------------------------|
| Supply voltage | 7 V DC 12 V DC |
| Recommended supply voltage | 8 V DC |
| Current consumption | 80 mA ¹⁾ |

¹⁾ Without load.

| Output frequency for sine/cosine signals | ≤ 200 kHz |
|--|-----------|
|--|-----------|

¹⁾ Without load.

Mechanical data

| Shaft version | Tapered shaft |
|--|------------------------------------|
| Flange type / stator coupling | Rubber support, Rubber support |
| Dimensions | See dimensional drawing |
| Weight | ≤ 0.2 kg |
| Moment of inertia of the rotor | 10 gcm ² |
| Operating speed | ≤ 12,000 min ⁻¹ |
| Angular acceleration | ≤ 200,000 rad/s² |
| Operating torque | 0.2 Ncm |
| Start up torque | + 0.4 Ncm |
| Permissible movement static | ± 0.3 mm radial ± 0.75 mm axial |
| Permissible movement dynamic | ± 0.1 mm radial ± 0.2 mm axial |
| Angular motion perpendicular to the rotational axis, static | ± 0.005 mm/mm |
| Angular motion perpendicular to the rotational axis, dynamic | ± 0.0025 mm/mm |
| Life of ball bearings | 3.6 x 10 ⁹ revolutions |

Ambient data

| Operating temperature range | −30 °C +115 °C |
|---|--|
| Storage temperature range | -40 °C +125 °C, without package |
| Relative humidity/condensation | 90 %, Condensation not permitted |
| Resistance to shocks | 100 g, 10 ms, 10 ms (according to EN 60068-2-27) |
| Frequency range of resistance to vibrations | 20 g, 10 Hz 2,000 Hz (EN 60068-2-6) |
| EMC | According to EN 61000-6-2 and EN 61000-6-3 ¹⁾ |
| Enclosure rating | IP40, with mating connector inserted (IEC 60529) |

¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

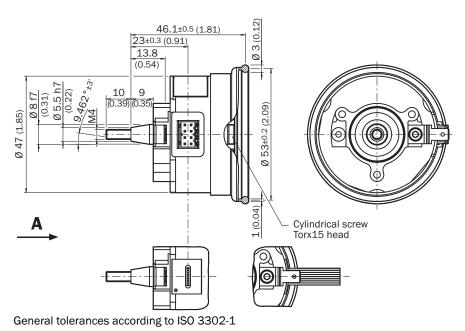
Classifications

| ECLASS 5.0 | 27270590 |
|--------------|----------|
| ECLASS 5.1.4 | 27270590 |
| ECLASS 6.0 | 27270590 |
| ECLASS 6.2 | 27270590 |
| ECLASS 7.0 | 27270590 |
| ECLASS 8.0 | 27270590 |
| ECLASS 8.1 | 27270590 |
| ECLASS 9.0 | 27270590 |
| ECLASS 10.0 | 27273805 |

| ECLASS 11.0 | 27273901 |
|----------------|----------|
| ECLASS 12.0 | 27273901 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| ETIM 7.0 | EC001486 |
| ETIM 8.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

Dimensional drawing (Dimensions in mm (inch))

Rubber support, tapered shaft



PIN assignment

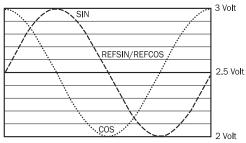


| PIN | Signal | Wire colors (cable connection) | Explanation |
|-----|----------------|--------------------------------|--------------------------|
| 1 | U _S | Red | Supply voltage |
| 2 | GND | Blue | Ground connection |
| 3 | REFSIN | Brown | Process data channel |
| 4 | REFCOS | Black | Process data channel |
| 5 | Data + | Gray or yellow | Parameter channel RS 485 |
| 6 | Data - | Green or purple | Parameter channel RS 485 |

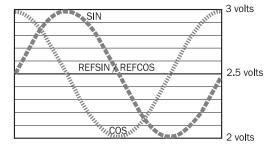
| PIN | Signal | Wire colors (cable connection) | Explanation |
|-----|--------|--------------------------------|----------------------|
| 7 | + SIN | White | Process data channel |
| 8 | + COS | Pink | Process data channel |

Diagrams

Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = 360° : 1024° Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = 360° : 1024°



Recommended accessories

Other models and accessories \rightarrow www.sick.com/SRS_SRM50

| | Brief description | Туре | Part no. |
|-------------------------------------|---|--------------|----------|
| Programming and configuration tools | | | |
| (e. 3) | SVip® LAN programming tool for all motor feedback systems | PGT-11-S LAN | 1057324 |
| Spare parts | | | |
| | BEF-MK-S02 | BEF-MK-S02 | 2074582 |

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