



DFV60B-22EZ0-S03

DFV60

MEASURING WHEEL ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	Part no.
DFV60B-22EZ0-S03	1051292

DFV60 spring arm (part number: 2056155) not included with delivery

Other models and accessories → www.sick.com/DFV60

Detailed technical data

Features

Special device	✓
Specialty	M12 male connector, 5-pin
Items supplied	DFV60 spring arm (part number: 2056155) not included with delivery

Performance

Pulses per revolution	1,500
Resolution in pulses/mm	5 Pulses/mm ¹⁾
Measuring increment (resolution in mm/pulse)	0.2 mm/pulse ²⁾
Measuring step deviation	± 0.08° ³⁾
Error limits	± 0.03°, ± 4 mm/m, subject to measuring wheel (measuring wheel surface + measuring surface + ambient conditions)
Initialization time	30 ms

¹⁾ Calculation example: Pulses per revolution / measuring wheel circumference = 16,384 pulses per revolution / 200 mm = 81.92 pulses/mm.

²⁾ Calculation example: Circumference of wheel / pulses per revolution = 200 mm / 16384 pulses per revolution = 0,012mm/pulse.

³⁾ Value refers to the mounted encoder.

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull

Electrical data

Operating power consumption (no load)	40 mA
Connection type	Male connector, M12, 5-pin, radial
Power consumption max. without load	≤ 30 mA
Supply voltage	10 V ... 32 V
Load current max.	30 mA
Maximum output frequency	820 kHz
Reference signal, number	1

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) ¹⁾

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Mechanical data

Measuring wheel circumference	300 mm
Measuring wheel surface	O-ring NBR70 ¹⁾
Mass	+ 420 g
Encoder material	
Shaft	Stainless steel
Flange	Aluminum
Housing	Aluminum
Cable	PUR
Spring arm mechanism material	
Spring element	Not contained in the scope of delivery of the system
Measuring wheel, spring arm	Aluminum
Start up torque	0.8 Ncm (at 20 °C)
Operating torque	0.6 Ncm (at 20 °C)
Operating speed	3,000 min ⁻¹
Maximum operating speed	1,500 min ⁻¹ ²⁾
Bearing lifetime	3 x 10 ⁹ revolutions
Maximum travel/deflection of spring arm	40 mm
Recommended pretension	20 Nm
Max. permissible working area for the spring (continuous operation)	± 10 mm
Recommended spring deflection	20 mm ... 40 mm
Mounting position relative to the measuring object	Preferably from above, from below possible

¹⁾ The surface of a measuring wheel is subject to wear. This depends on contact pressure, acceleration behavior in the application, traversing speed, measurement surface, mechanical alignment of the measuring wheel, temperature, and ambient conditions. We recommend you regularly check the condition of the measuring wheel and replace as required.

²⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-4
Enclosure rating	IP65
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-20 °C ... +100 °C
Storage temperature range	-40 °C ... +100 °C, without package

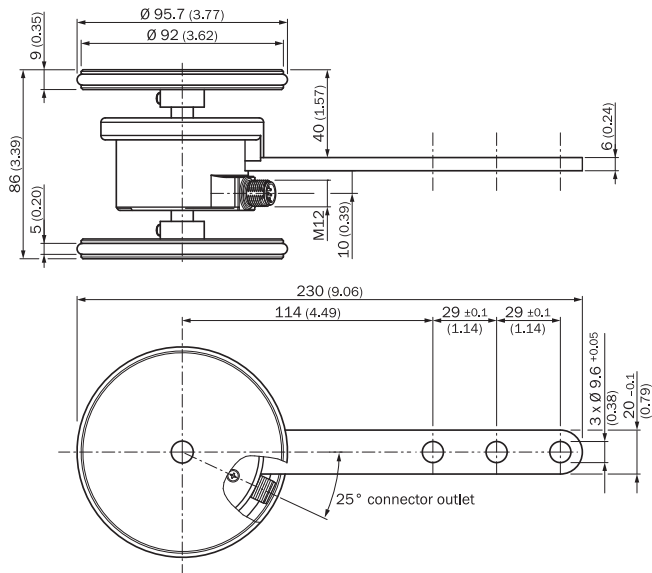
Classifications

ECLASS 5.0	27270501
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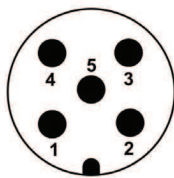
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270507
ECLASS 12.0	27270504
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

DFV60



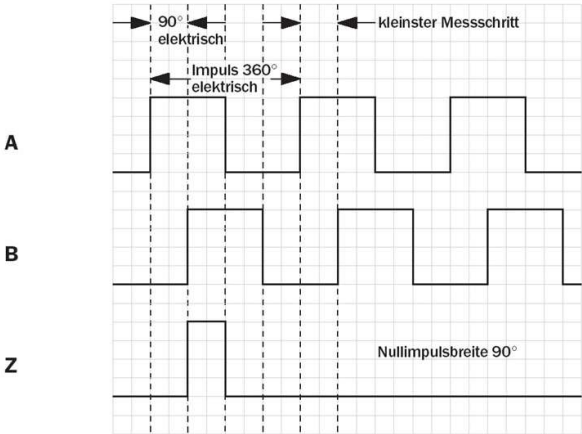
PIN assignment



View to the connector M12 fitted to the encoder body

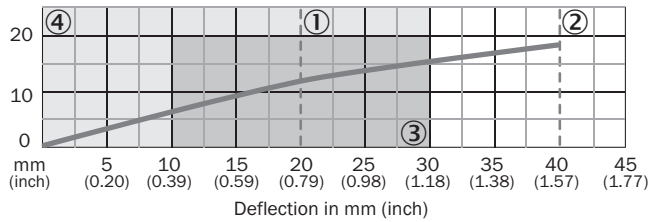
PIN	Signal	Description
1	Us	Supply voltage (potential free to housing)
2	B	Signal line
3	GND	Ground connection of the encoder
4	A	Signal line
5	Z	Signal line for zero pulse

Diagrams

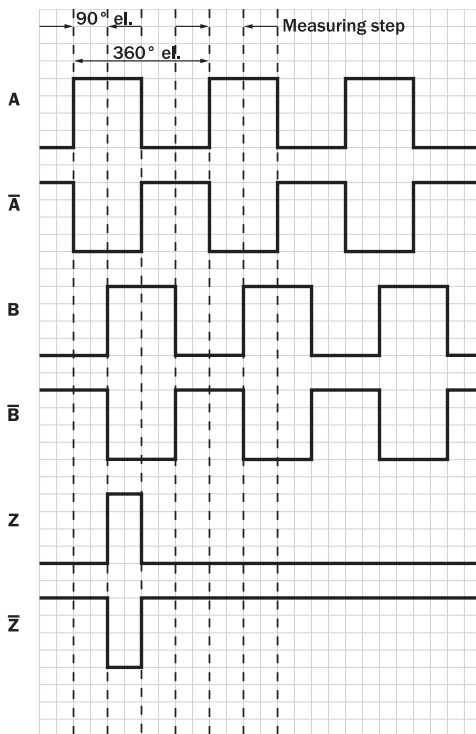


Dual wheel, spring tension, yoke mount

Force in N



- ① Recommended pre-tension (20 mm)
- ② Maximum deflection (40 mm)
- ③ Recommended deflection range (10 – 30 mm)
- ④ Permissible working area (0 – 30 mm)



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