

DBS60E-BEFAK0S86

DBS60

INCREMENTAL ENCODERS



Illustration may differ

Ordering information

Туре	Part no.
DBS60E-BEFAKOS86	1092027

Other models and accessories → www.sick.com/DBS60



Detailed technical data

Features

Special device	√	
Specialty	Customer-specific pin assignment	
Standard reference device	DBS60E-BEFAK0360	

Performance

Pulses per revolution	360
Measuring step	≤ 90°, electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL 1)
Number of signal channels	6-channel
Initialization time	< 5 ms ²⁾
Output frequency	+ 300 kHz ³⁾
Load current	≤ 30 mA, per channel
Power consumption	≤ 0.5 W (without load)

 $^{^{1)}}$ Output level depends on the supply voltage.

Electrical data

Connection type	Male connector, M23, 12-pin, radial, Customer-specific pin assignment	
Supply voltage	4.5 30 V	
Reference signal, number	1	
Reference signal, position	90°, electric, logically gated with A and B	
Reverse polarity protection	✓	

 $^{^{1)}\,\}mbox{Short-circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

 $^{^{\}rm 2)}\,{\rm Valid}$ signals can be read once this time has elapsed.

 $^{^{\}rm 3)}$ Up to 450 kHz on request.

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Short-circuit protection of the outputs	✓ ¹⁾
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) ²⁾

 $^{^{1)}\,\}mbox{Short-circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

Mechanical data

Mechanical design	Blind hollow shaft	
Shaft diameter	12 mm	
Flange type / stator coupling	Without stator coupling, flange with 3 x M3, 3 x M4, axial register pin mounting, for 4 mm register pin	
Weight	+ 0.25 kg ¹⁾	
Shaft material	Stainless steel	
Flange material	Aluminum	
Housing material	Aluminum	
Start up torque	+ 0.5 Ncm (+20 °C)	
Operating torque	0.4 Ncm (+20 °C)	
Permissible movement static	\pm 0.3 mm (radial) \pm 0.5 mm (axial) ²⁾	
Permissible movement dynamic	\pm 0.1 mm (radial) \pm 0.2 mm (axial) ²⁾	
Operating speed	6,000 min ^{-1 3)}	
Maximum operating speed	9,000 min ⁻¹ ⁴⁾	
Moment of inertia of the rotor	50 gcm ²	
Bearing lifetime	3.6 x 10 ⁹ revolutions	
Angular acceleration	≤ 500,000 rad/s²	

 $^{^{1)}}$ Based on encoder with male connector or cable with male connector.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3	
Enclosure rating	IP67, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)	
Permissible relative humidity	90 % (Condensation not permitted)	
Operating temperature range	-30 °C +100 °C, at maximum 3,000 pulses per revolution ²⁾	
Storage temperature range	-40 °C +100 °C, without package	
Resistance to shocks	250 g, 3 ms (EN 60068-2-27)	
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)	

¹⁾ With mating connector fitted.

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 $^{^{2)}\,\}mathrm{Not}\,\mathrm{apllicable}$ for stator coupling type C and K.

 $^{^{}m 3)}$ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

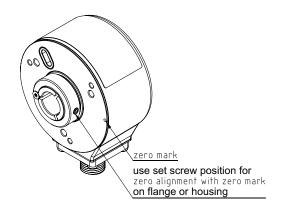
⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

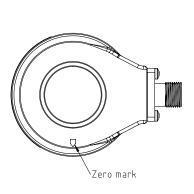
²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

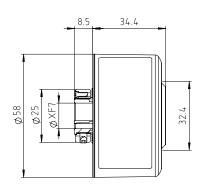
Classifications

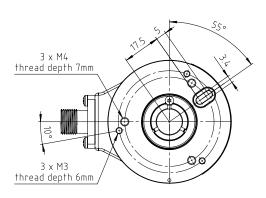
ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))



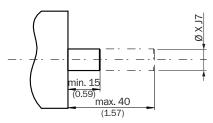






Attachment specifications

Blind hollow shaft



Customer side

Type Blind hollow shaft	Shaft diameter xj7
DBS60x-BAxxxxxxxx DBS60x-B1xxxxxxxxx	6 mm
DBS60x-BBxxxxxxxx DBS60x-B2xxxxxxxx	8 mm
DBS60x-BCxxxxxxxx DBS60x-B3xxxxxxxxx	3/8"
DBS60x-BDxxxxxxxx DBS60x-B4xxxxxxxx	10 mm
DBS60x-BExxxxxxxx DBS60x-B5xxxxxxxxx	12 mm
DBS60x-BFxxxxxxxx DBS60x-B6xxxxxxxxx	1/2"
DBS60x-BGxxxxxxxx DBS60x-B7xxxxxxxxx	14 mm
DBS60x-BHxxxxxxxx DBS60x-B8xxxxxxxxx	15 mm
DBS60x-BJxxxxxxxx	5/8"

PIN assignment

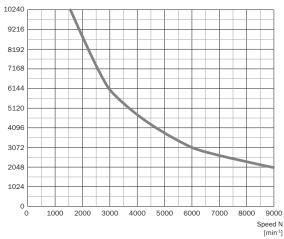
View of M23 device connector on cable cable/housing



Signal TTL, HTL	Explanation
A_	Signal line
+U _S	Supply voltage
Z	Signal line
Z_	Not connected
В	Signal line
B_	Signal line
Not connected	Not connected
A	Signal line
Screen	Screen connecte to encoder housing
GND	Ground connecion of the encoder
Not connected	Not connected
Not connected	Not connected
	A_ +U _S Z

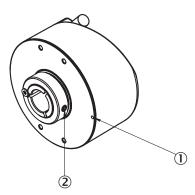
Diagrams





Operation note

Hollow shaft



Attention! If stator coupling is mounted, the zero pulse mark can be hidden by the stator coupling

- ① Zero pulse mark on flange
- ② Zero pulse is active when screw of clamping is inline with zero pulse mark on flange or housing mark

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